

سليم وصالح المختار خزياء عرب وفيل ...

السؤال الأول:

(b) أو 2s

(b) أو 1

(c) أو 1

(a) أو 1

(b) أو 0.4

السؤال الثاني: وهي معادلة تفاضلية من الدرجة

الدرجة تقبل حلاً عاماً من الشكل:

$$\theta = \theta_{\max} \cos(\omega_0 t + \phi)$$

نصف حركتين:

$$(4) \theta'_t = \dot{\omega} = -\omega_0 \theta_{\max} \sin(\omega_0 t + \phi)$$

$$(4) \theta''_t = \alpha = -\omega_0^2 \theta_{\max} \cos(\omega_0 t + \phi)$$

$$(4) \theta'''_t = \alpha = -\omega_0^2 \theta \dots (2)$$

بالطريقة:

$$-\omega_0^2 \theta = -\frac{K}{I_D} \theta$$

$$\omega_0^2 = \frac{K}{I_D} \Rightarrow \omega_0 = \sqrt{\frac{K}{I_D}} > 0$$

لأن K و I_D مقدور موجبة.

$$\omega_0 = \frac{2\pi}{T_0} \Rightarrow T_0 = \frac{2\pi}{\omega_0} = \frac{2\pi}{\sqrt{\frac{K}{I_D}}}$$

$$\Rightarrow T_0 = 2\pi \sqrt{\frac{I_D}{K}}$$

السؤال الثالث:

$$(5) x = x_{\max} \cos(\omega_0 t)$$

$$(3) v = (x)'_t = -\omega_0 x_{\max} \sin(\omega_0 t) \quad (10)$$

$$(2) a = (x)''_t = -\omega_0^2 x_{\max} \cos(\omega_0 t) \quad (10)$$

$$(5) a = -\omega_0^2 x \quad (10)$$

$$(3) \cos(\omega_0 t) = \pm 1 \text{ عندما } \dots (10)$$

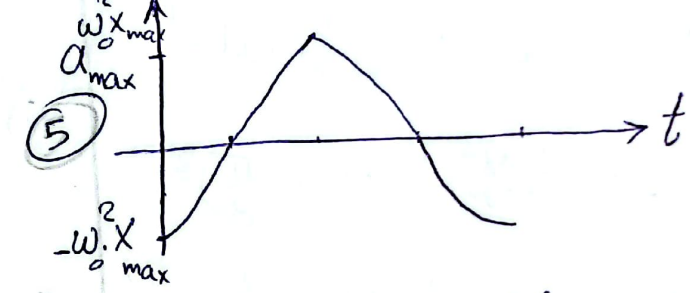
$$\Rightarrow x = \pm x_{\max} \quad (10)$$

$$(2) \text{ في الوترين المرفقين.}$$

$$(3) \cos(\omega_0 t) = 0 \text{ عندما } \dots (10)$$

$$\Rightarrow x = 0 \quad (10)$$

$$(2) \text{ في مركز التوازن}$$



الاننا: المسألة الأولى

$$(5) I_D = \frac{1}{12} m l^2 \quad (11)$$

$$(3) = \frac{1}{12} (0.3) (20 \times 10^{-2})^2 = \frac{1}{4} \times 10^{-1} \times 4 \times 10^{-2} \quad (4)$$

$$(2) \Rightarrow I_D = 10^{-3} \text{ Kg.m}^2$$

$$(2+3+5) T_0 = 2\pi \sqrt{\frac{I_D}{K}} = 2\pi \sqrt{\frac{10^{-3}}{10^{-2}}} = 2s \quad (2)$$

$$(5) \theta = \theta_{\max} \cos(\omega_0 t + \phi)$$

$$(3) \theta = \theta_{\max} = \frac{\pi}{4} \text{ rad}$$

$$\textcircled{5} \omega_0 = \frac{2\pi}{T_0} = \frac{2\pi}{2} = \pi \text{ rad s}^{-1} \textcircled{2}$$

① ($t=0, \theta = \theta_{max}$)

② $\theta_{\max} = \theta_{\max} \cos \phi$

$\frac{\pi}{4} = \frac{\pi}{4} \cos \phi \Rightarrow \cos \phi = 1$

② $\phi = 0 \text{ rad}$

⑤ $\Rightarrow \theta = \frac{\pi}{4} \cos(\pi t)$

$$t_2 = \frac{3T_0}{4} = \frac{3(2)}{4} = \frac{3}{2} \text{ s}$$

$$\textcircled{5} \omega = -\omega_0 \theta_{\max} \sin(\omega_0 t_2 + d)$$

$$\boxed{2} \quad 2+3 = -\pi \times \frac{\pi}{4} \sin\left(\pi, \frac{3}{2}\right) = -\frac{10}{4}(-1)$$

$$\Rightarrow \omega = \frac{10}{4} = \frac{5}{2} \text{ rad.s}^{-1}$$

$$(5) E_p = \frac{1}{2} k \theta^2 = \frac{1}{2} (10^{-2}) \left(\frac{\pi}{8} \right)^2$$

$$= \frac{1}{2} \times 10^{-2} \times \frac{10}{64} = \frac{10^{-1}}{128} \text{ J}$$

$$\textcircled{5} E_K = E - E_p$$

$$\textcircled{5} E = \frac{1}{2} K \theta_{\max}^2 = \frac{1}{2} (10^{-2}) \left(\frac{\pi}{4} \right)^2$$

$$= \frac{1}{2} \times 10^{-2} \times \frac{10}{16} = \frac{10^{-1}}{32} \text{ J}$$

3) $2+3$

$$\textcircled{21} E_K = \frac{1}{32} \times 10^{-1} - \frac{1}{128} \times 10^{-1} = \frac{3}{128} \times 10^{-1} \text{ J}$$

$$\textcircled{21} E_K = \frac{1}{32} \times 10^{-1} - \frac{1}{128} \times 10^{-1} = \frac{3}{128} \times 10^{-1} \text{ J}$$

$$(2+3) W = -\pi \cdot \frac{\pi}{3} \sin\left(\pi \times \frac{5}{2}\right) = -\frac{10}{3} \text{ rad.s}^{-1}$$

$$\textcircled{5} \textcircled{2} = \frac{\pi}{4} \cdot 8 \times 10^{-2} = 2\pi \times 10^{-2} \text{ m.s}^{-1}$$

$$\textcircled{5} T_0 = 2\pi \sqrt{\frac{m}{K}}$$

$$T_0^2 = 40 \cdot \frac{m}{K} \Rightarrow K = \frac{40 \cdot m}{T_0^2}$$

$$\textcircled{2+5} K = \frac{40 \times 10^{-1}}{64} = \frac{1}{16} \text{ N.m}^{-1}$$

$$\textcircled{3} a = -\omega_0^2 x$$

$$\textcircled{2} = -\left(\frac{\pi}{4}\right)^2 \cdot 5 \times 10^{-2}$$

$$\textcircled{1} = -\frac{5}{160} = -\frac{1}{32} \text{ m.s}^{-2}$$

$$\textcircled{3} F = -Kx$$

$$\textcircled{2} = -\frac{1}{16} \times 5 \times 10^{-2} = -\frac{5}{1600}$$

$$\textcircled{1} = -\frac{1}{320} \text{ N}$$

$$\textcircled{3} E_{\text{tot}} = \frac{1}{2} K X_{\text{max}}^2$$

$$\textcircled{2} = \frac{1}{2} \times \frac{1}{16} (8 \times 10^{-2})^2$$

$$\textcircled{2} = \frac{1}{32} \times 64 \times 10^{-4} = 2 \times 10^{-4} \text{ J}$$

$$\textcircled{3} E_k = E_{\text{tot}} - E_p$$

$$\textcircled{2} E_p = \frac{1}{2} K x^2 = \frac{1}{2} \times \frac{1}{16} (4 \times 10^{-2})^2$$

$$\textcircled{3} \textcircled{2} = 5 \times 10^{-5} \text{ J}$$

$$\textcircled{2} E_k = 2 \times 10^{-4} - 5 \times 10^{-5} = 1.5 \times 10^{-4} \text{ J}$$

$$l' = \frac{l}{4} \Rightarrow \frac{T_0'}{T_0} = \sqrt{\frac{l'}{l}} \quad \textcircled{4}$$

$$\textcircled{3} \frac{T_0'}{T_0} = \sqrt{\frac{l/4}{l}} \Rightarrow \frac{T_0'}{T_0} = \sqrt{\frac{1}{4}}$$

$$\textcircled{2} \Rightarrow \frac{T_0'}{T_0} = \frac{1}{2}$$

$$\textcircled{2} T_0' = \frac{T_0}{2} = \frac{8}{2} = 4 \text{ s}$$

السؤال الثاني:

$$\textcircled{5} x = X_{\text{max}} \cos(\omega_0 t + \phi) \quad \textcircled{1}$$

$$\textcircled{3} d = 16 \text{ cm} \Rightarrow d = 2X_{\text{max}} \\ X_{\text{max}} = \frac{d}{2} = \frac{16 \times 10^{-2}}{2}$$

$$\textcircled{2} = 8 \times 10^{-2} \text{ m}$$

$$\textcircled{1} (t=0, x = \overset{-X_{\text{max}}}{\uparrow})$$

في أقصى نقطة

$$\textcircled{5} \textcircled{3} -X_{\text{max}} = X_{\text{max}} \cos \phi \\ \Rightarrow \cos \phi = -1$$

$$\textcircled{2} \phi = \pi \text{ rad}$$

$$\textcircled{5} t = \frac{T_0}{2} \Rightarrow 4 = \frac{T_0}{2} \Rightarrow T_0 = 8 \text{ s}$$

$$\textcircled{2} \omega = \frac{2\pi}{T_0} = \frac{2\pi}{8} = \frac{\pi}{4} \text{ rad.s}^{-1}$$

$$\textcircled{5} x = 8 \times 10^{-2} \cos\left(\frac{\pi}{4} t + \pi\right)$$

$$\textcircled{3} t_1 = \frac{T_0}{4} = \frac{8}{4} = 2 \text{ s}$$

$$\textcircled{5} V_{\text{max}} = \omega_0 X_{\text{max}}$$

②

$$-\frac{K}{I_D} \cdot \theta = -\omega_0^2 \theta$$

$$(5) \quad \omega_0^2 = \frac{K}{I_D} \Rightarrow \omega_0 = \sqrt{\frac{K}{I_D}} > 0$$

$$(5) \quad \Rightarrow \text{حركة توافقية بسيطة} \\ \text{فولانية}$$

أ. فأين قبل ...
أ. أعل أعوان ...

$$(2) \quad E_{tot} = E_p + E_k = \text{const} \quad \text{المسألة الرابع}$$

$$(2) \quad E_{tot} = \frac{1}{2} K \cdot \theta^2 + \frac{1}{2} I_D \cdot \omega^2$$

النسبة بالزمن:

$$(1) \quad 0 = \frac{1}{2} K (2\theta) (\omega) + \frac{1}{2} I_D \cdot 2\omega (\alpha)$$

$$0 = K \cdot \theta \cdot \omega + I_D \cdot \omega \cdot \alpha$$

(ن: ω)

$$0 = K \cdot \theta + I_D \cdot \alpha$$

$$(3) \quad I_D \cdot \alpha = -K \theta$$

$$(2) \quad \alpha = -\frac{K}{I_D} \cdot \theta$$

$$(3) \quad (\theta)_t'' = -\frac{K}{I_D} \cdot \theta \quad \dots (1)$$

(1) وفي معادلة تفاضلية من الدرجة الثانية قبل
لا حلاً جدياً من (1):

$$(5) \quad \theta = \theta_{max} \cos(\omega_0 t + \phi) \quad \text{(نصف حزين)}$$

$$(2) \quad \omega = (\theta)_t' = -\omega_0 \cdot \theta_{max} \sin(\omega_0 t + \phi)$$

$$(2) \quad \alpha = (\theta)_t'' = -\omega_0^2 \cdot \theta_{max} \cos(\omega_0 t + \phi)$$

$$(2) \quad (\theta)_t'' = -\omega_0^2 \cdot \theta \quad \dots (2)$$

المطابقة بين (1) و (2) في أن: